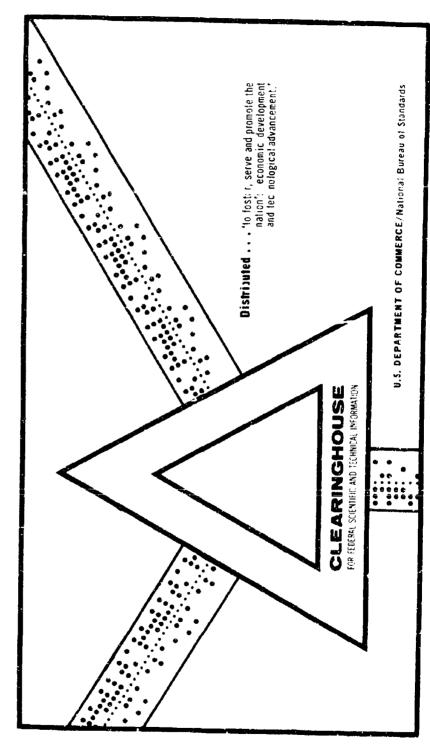
ELF PROPAGATION AND EMISSION IN THE MAGNETOSPHERE

. B. Liemohn

Boeing Scientific Research Laboratories Scattle, Washington

October 1969



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H. B. Liemohn

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AUGUST 1989

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ELF PROPAGATION AND EMISSION IN THE MAGNETOSPHERE

bу

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August 1969

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ELF PROPAGATION AND EMISSION IN THE MAGNETOSPHERE

by

H. B. Liemohn

ABSTRACT

Considerable research progress has been achieved on ELF signals in the magnetosphere as a consequence of satellite and ground-based studies. Attention will be focused on the frequency band from C.2 to 500 Hz, which is well below the minimum electron plasma and cyclotron frequencies, so that the hydromagnetic approximation applies. Although the magneto-ionic medium is anisotropic and inhomogeneous, the propagation theory for the fast and Alfvén modes in homogeneous media is adequate at these frequencies. The signal velocity of the fast mode is essentially isotropic for frequencies below the lower hybrid resonance. The Alfvén mode is restricted to frequencies below the proton cyclotron frequency and its signal velocity is closely guided by the geomagnetic field. The polarization of the modes is nominally right and left for the fast and Alfvén, respectively, and circular only for propagation parallel to the field.

The morphology of these modes in remote regions of the magnetosphere is being developed from satellite studies. Statistics are available now on the ELF noise distributions with latitude, local time, and geomagnetic activity. Triaxial search coil magnetometers have measured wave polarization and found it to be predominantly right handed above the local proton cyclotron frequency. The noise power spectrum near the magnetosheath is similar to that observed on the ground. During magnetospheric substorms the noise level increases as anticipated.

Studies based on ground observations have concentrated on dispersion, polarization, and amplitude analyses. Due to ionospheric attenuation, ground observations of ELF signals from the magnetosphere are limited to frequencies below about 10 Hz. In the band from 0.2 to 10 Hz, however, many types of geomagnetic micropulsation signals are observed. The characteristic dispersion of one class of signals led to its interpretation as Alfvén-mode waves which propagate back and forth along field-line paths. These "ULF whistlers" are sufficiently well documented to permit their use as magnetospheric probes of the thermal plasma distribution. Polarization studies have attempted to isolate the propagation modes, but coupling in the ionosphere has hampered progress. Signal amplification by the cyclotron-resonance interaction with energetic particles, and attenuation in the ionospheric waveguide have been extensively investigated theoretically.

Several recommendations concerning future research may be offered.

Foremost among them is the necessity for more cooperative programs

between research groups due to the global nature of the phenomena. To

this end, up-to-date tabulations of ground stations and satellites have

been prepared, and more emphasis could be placed on "regular geophysical

days." Calibrated amplitude spectra are needed in view of their

potential as remote sensing parameters. Similarly polarization properties

are vital to the interpretation of signals. Finally, the establishment

of remote ground stations in uninhabited locations should be considered.

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INTRODUCTION

The purpose of this paper is to succinctly summarize current research on extremely low frequency (ELF) propagation and emission in the magnetosphere. The topic is restricted to satellite research in the frequency band from 0.2 to 500 Hz and ground-based research in the band from 0.2 to 10 Hz. ELF signals are observed primarily as rapid variations in the geomagnetic field using various magnetometers. A wide range of signal characteristics are encountered depending on the modes of propagation, source mechanisms, and local conditions along the propagation path. These properties permit the signals to be used as remote sensors of several important magnetospheric parameters which is the motivation for this research.

Several comprehensive reviews of ground-based research in this field have appeared in recent years (1-8). The reader who wants to pursue some aspect of this subject in depth is directed to these detailed compendia as well as the original literature. More recent satellite results at these frequencies have not been formally reviewed, but excellent summaries of the scientific results from magnetometer experiments in the OGO series are now available (9,10).

A large amount of very good research has been performed in the field of ELF propagation, as evidenced by the long reference lists in review papers. In an effort to make this summary more readable, the references to recent original literature have been collected at the beginning of each short subsection. No attempt will be made to cite individual research results as is customary in comprehensive reviews. The subsections of this paper are collected under four main sections: propagation theory, satellite studies, ground studies, and future research.

PROPAGATION THEORY

Hydromagnetic approximation. The propagation of ELF signals in the magnetosphere is usually described by the hydromagnetic approximation in which the inertial effects of the electrons are ignored, since the frequencies of interest are well below the electron plasma and cyclotron frequencies $^{\rm II}_{\rm e}$ and $^{\rm O}_{\rm e}.$ In general there are three modes of propagation in a magnetoionic medium, namely, two electromagnetic waves with transverse fields and an acoustic wave. In this approximation the mode that is polarized in the left-hand sense is called the "Alfvén" mode, the mode with right-hand polarization is called the "fast" mode, and the acoustic mode is called the "slow" mode. The mathematical description of these modes varies considerably depending on the assumptions about the medium.

The simplest description is obtained for propagation in a homogeneous cold plasma when the frequencies are well below the ion plasma and cyclotron frequencies, $\Pi_{\bf i}$ and $\Omega_{\bf i}$. The modes in the well-known case (11, 12), in which the medium is treated like a compressible, conducting fluid, are shown schematically in Figure 1. The phase velocity surfaces depend

Hydromagnetic Propagation Modes

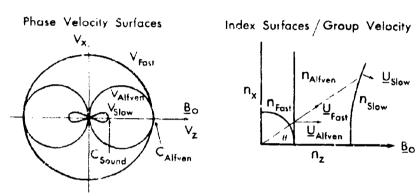


Fig. 1. Schemetic diagram of hydromagnetic wave propagation modes at frequencies well below the ion-cyclotron frequency.

chiefly on the Alfvén speed $V_A = B_0/(4\pi\rho_0)^{\frac{1}{2}}$ and the sound speed $V_S = (\gamma p_0/\rho_0)^{\frac{1}{2}}$ where B_0 is the static field, ρ_0 is the ion-mass density, ρ_0 is the static gas pressure and γ is the ratio of specific heats. For quantities appropriate to the magnetosphere, $V_A >> V_S$ so that the slow mode may be ignored in most applications. The mode characteristics shown in Figure 1 are typical of ELF propagation in the lower magnetosphere and ionosphere. Although the medium is anisotropic, the signal velocity of the fast mode is essentially isotropic whereas the signal velocity of the Alfvén mode is closely guided by the magnetic field.

In remote regions of the magnetosphere, near its boundary and In the tail, the frequencies of interest are close to both $\frac{1}{1}$ and $\frac{1}{1}$ which require more elaborate formulation (13-16) of the cold plasma approximation. In this parameter regime the wave normal surfaces and group velocity surfaces are distorted considerably from the simple case. The Alfvén mode is restricted to frequencies below $\frac{1}{1}$ where it has a resonance, and its group velocity remains closely guided along the field. The fast mode remains unrestricted up to the lower hybrid resonance frequency $\frac{1}{1}$, where a cone of forbidden wave normals is encountered perpendicular to the

static field. However, fast mode signals continue to propagate at large angles to the field at frequencies up to Ω .

Applications. Certain aspects of hydromagnetic propagation in the magnetosphere and ionosphere have received special attention. In the magnetosphere, field-line guidance of Alfvén waves has been investigated (17-19) to ascertain the effects of inhomogeneity. Ray path calculations in a realistic geomagnetic field have shown that the field curvature does not appreciably diverge the signal away from the field. Guidance by field-aligned ducts of enhanced or depressed ionization is also feasible but apparently not essential.

Propagation in and through the ionosphere has been a particularly vexing problem due to the complications of mode coupling and guiding as well as the usual transmission, reflection, and absorption processes. Absorption of hydromagnetic energy is known to increase rapidly with frequency producing an upper limit near 10 Hz in ground observations. Just below this cutoff, the ionosphere remains relatively opaque to direct wave penetration, and instead the hydromagnetic energy is confined to a waveguide shell between 100 and 1000 km from which it leaks to the ground. Since ionospheric quantities

have steep gradients, a full-wave treatment with its attendant numerical methods is mandatory.

Refinements in the attenuation theory have produced more realistic estimates (20-23) of direct transmission properties. There is a large diurnal variation with maximum absorption during the daytime. However, ionospheric heating by ELF waves is negligible compared to other sources except possibly during geomagnetic storms. The physics of the ionospheric waveguide has been developed extensively as well (24-28). In the waveguide the fast mode has a group velocity of around 600 km/s and is strongly attenuated during the day. Enhanced attenuation below 0.5 Hz effectively band limits the mode for long distance transmission. Coupling between the Alfvén and fast modes is sharply peaked in the lower F-region permitting large amounts of Alfvén wave energy from the magnetosphere to enter the waveguide. However, realistic estimates of the net reflection and transmission of energy by the ionosphere remain uncertain due to the large number of independent parameters.

Wave-Partiale Interactions. Research on hot plasma effects at these frequencies has centered on the cyclotron-resonance interaction. Due to motion parallel to the static field, particles encounter a Doppler shifted wave frequency. When

this frequency equals the cyclotron frequency of the particle and the wave polarization as seen by the particle has the same sense as the particle gyration, the resonance takes place. Evidently both Alfvén and fast mode waves may interact with either protons or electrons. In practice the dominant interaction is between Alfvén waves and nonthermal protons (above 100 eV). The net amplification or attenuation of the waves depends critically on the shape of the particle distribution as well as the frequencies.

The cyclotron instability of particle streams in thermal background plasma has been suggested (29-31) as a source of hydromagnetic energy, but their generation and maintenance is unlikely. When the nonthermal proton distribution in the steady-state quiescent magnetosphere is sufficiently anisotropic, however, Alfvén mode waves may be strongly amplified (32-41). Examples of the power transfer for interhemisphere field-line paths are shown in Figure 2 for energy and pitch angle distributions of the form $E^{-n}\sin^m\alpha$. The waves are subject to Landau damping when their propagation vector is not parallel to the static field, but cyclotron resonance amplification still dominates if the energy q, withution is sufficiently hard.

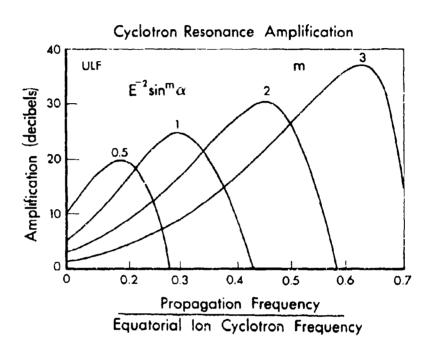


Fig. 2. Cyclotron-resonance amplification of hydromagnetic wave packets propagating along fieldline paths for specific energy (E) and Steh angle (a) distributions of ions (34).

Since the cyclotron resonance occurs over a broad range of particle energies, the interaction is capable of redistributing energy and modifying pitch angles (42-47). Using quasi-linear theory, the equilibrium configuration of waves and particles in the magnetosphere has been realistically estimated, but the complete nonlinear theory remains to be developed. The effects of the interaction have been evaluated statistically as well to ascertain diffusion rates parallel and orthogonal to the field. Cyclotron damping of magnetosonic waves may also heat the magnetospheric plasma differentially, accounting for the excess energy in the proton distribution in the neutral sheet of the tail.

Other mechanisms involving ELF waves also affect the waveparticle equilibrium in the magnetosphere (48-50). Random
scattering by hydromagnetic wave fields may be characterized
by a net diffusion coefficient in pitch angle. In addition
the mirror geometry of the geomagnetic field allows resonant
pitch-angle scattering at the bounce frequency of the particles.

SATELLITE STUDIES

Magnetosphere boundary. Several spacecraft carrying magnet...
ometers with ELF sensitivity have traversed the boundary region of
the magnetospheric cavity (51-57). The location of the magnetopause
and shock surfaces which bound the magnetosheath are easily
identified in satellite data so that the morphology of the
accompanying wave structure can be isolated. In the shock
transition region both random incoherent noise and discrete
coherent signals are found over the band from 0.1 to 500 Hz.
Above 10 Hz the power spectral density falls approximately
as (frequency)⁻³ and tends to flatten off below. The signals
are detected both upstream on the solar wind side and downstream
in the magnetosheath. The total energy density of these wave
fields is less than 1% of the average solar wind kinetic energy
density.

Since the amplitude of the signals decreases by one to two orders of magnitude away from the shock front, it is fair to assume that their source is in the shock mechanism. Below 10 Hz the discrete signals are contained in wave packets of only a few cycles with amplitudes as high as a gamma. Above 10 Hz

nearly monochromatic wave packets occur at random frequencies with amplitudes from 10 to 100 milligamma. Since these high frequency signals last several seconds in the magnetosheath, some amplification mechanism is suggested. The transverse polarization of these signals is approximately circular which suggests propagation in the fast and Alfvén modes.

Although insufficient parameters are available at this time to identify the modes, some speculation is feasible on the basis of what is known. The ambient magnetic field is about 30 gamma which gives $\Omega_1 \sim 0.5$ Hz, $\omega_{\rm LHR} \sim 20$ Hz and $\Omega_2 \sim 900$ Hz. There is evidence in the power spectra of the waves for changes of slope near 1 Hz and 30-100 Hz which may be attributed to the disappearance of the Alfvén mode above Ω_1 and reduced fast mode propagation above $\omega_{\rm LHR}$. In addition the relatively large amplitude of some signals near Ω_1 is suggestive of wave-particle interactions which could amplify the signals.

Magnetosphere. Reasurements of ELF (below 500 Hz) within the magnetosphere have not been analyzed extensively until quite recently (58,59). Inside the magnetopause there is a sharp decrease in wave energy density throughout the ELF band. Evidently very little shock wave energy penetrates this boundary

directly, and consequently a different source mechanism must account for the hydromagnetic energy inside the magnetosphere. Again the signals consist of both bursts and steady noise, but the predominant frequency regime is somewhat higher and the amplitude is lower than that in the boundary region.

The steady ELF noise about 10 Hz is generated principally on the dayside of the magnetosphere over the latitude region 10° to 50° on L-shells from 6 to 10 although strong signals are detected as low as L = 2. The source of this energy is probably a plasma instability at $\Omega_{\rm i}$ caused by a pitch angle anisotropy of the trapped particles. The frequency range and power of these waves seems to be sufficient to account for the steady electron precipitation in the energy range from 20 to 200 keV. Observations of ELF noise at the base of the magnetosphere are consistent with observations in the source region, but low altitude data alone provides an incomplete picture of ELF throughout the magnetosphere.

Bursts of ELF noise are found principally within 20° of the equator at L-shells beyond 5. There is a strong day-night asymmetry with most probably occurrence between 0400 and 1800 local time. This source region is consistent with the region where auroral microbursts of electrons and VLF chorus are found. This close association with related geomagnetic activity is evidently another manifestation of wave-particle interactions.

A different group of ELF signals has been discovered in the immediate vicinity of the equator just inside the plasmapause. The noise consists of a broad enhancement between $2\Omega_{i}$ and $\omega_{\rm LHR}$ with numerous discrete peaks. Incredible though it may seem these signals are only detected within 2° of the equator and propagate nearly perpendicular to the static field. Only the fast mode can satisfy these criteria. The amplitude of this noise is about 10 milligamma which is sufficient to produce the observed pitch angle diffusion of electrons mirroring near the equator.

GROUND STUDIES

Pc 1 Morphology. Our knowledge about the properties of continuous geomagnetic-pulsation trains in the ELF frequency band from 0.2 to 10 Hz (Pc 1 class) has continued to grow from ground station observations. Many types of signal noise are observed in the Pc 1 category, but one unusual type has been singled out for extensive study due to its measurable structure. This section is concerned only with the morphology of these signals leaving discussions of dispersion, polarization, and amplification to later subsections.

The type of Pc 1 events under study consist of a series of rising tones over a narrow bandwidth that repeat at regular intervals which is illustrated in Fig. 3. The event is interpreted (60, 61) as an Alfvén mode wave packet that propagates back and forth along a field-line path producing multihop echoes at the ground station The spacing of 2 to 4 minutes between elements is indicative of a group velocity around 300 km/s along the path. Frequently the events occur in complicated overlapping clusters of events which may last for several hours. The characteristic ascending tone is attributed to the frequency-time dispersion inherent in the mode. At the base of the path, the energy scatters into the ionosphere waveguide and subsequently leaks to the ground over a broad area. On the ground the signal amplitudes are normally a few tens of milligammas so that their amplitude in the magnetosphere must be close to a gamma. Although the explanation for these events seems well established, their impulsive source has not been determined. In the course of research these events have been called pearls, hydromagnetic emissions, screamers, micropulsation whistlers, hydromagnetic whistlers, and ULF whistlers, and their nomenclature remains unsettled at this time. For purposes of identification the name ULF whistlers will be used here.

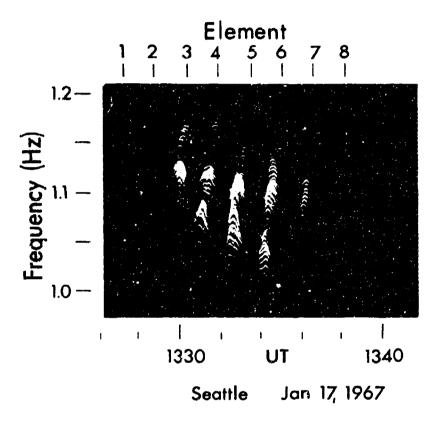


Fig. 3. Ampligram display of a typical ULF whistler event (91, 92).

One phase of research on these signals has concentrated on general patterns of frequency, occurrence, and conjugacy (62-71). On the basis of ground observations at several locations, the propagation frequency was recognized as a significant measure of the path location. Empirically it was found that frequencies from 0.3 to 3 Hz corresponded to L-shell paths from 10 to 4 respectively. The occurrence of ULF whistlers varies with latitude, and a diurnal pattern has been established that is similar to the auroral oval, that is, lower invariant latitude at night than day. The appearance of the wave packet in alternate hemispheres is not exactly 180° out of phase, but discrepancies are attributed to differences of travel time in the ionospheric waveguide. Ionospheric attenuation has been estimated experimentally by comparing simultaneous events at conjugate stations where the ionosphere above one was never sunlit; the amplitude ratios decreased during the daytime and also with increasing frequency in agreement with theoretical predictions.

Correlations between ULF whistlers and other types of geophysical phenomena have also received considerable attention (72-76). Special significance must be accorded the fact that these events occur principally during the calm period 3 to 7 days after a geomagnetic storm. It is not clear whether source, propagation, or

amplification conditions are responsible for this circumstance, but evidently the temporary state of magnetospheric relaxation is vital. A positive correlation with magnetospheric substorms is in doubt, although some ULF whistlers have been observed during these periods of activity. Other types of geomagnetic micropulsations do appear to be well correlated with substorms. Over the eleven-year solar cycle, the occurrence of these signals peaks sharply around the inflection points intermediate between solar-cycle extrema, which indicates a complicated secondary dependence on geomagnetic storm physics.

ULF Whistler Dispersion. Nearly all measurable events exhibit a small dispersion between successive elements which is attributed to the frequency dependence of the Alfvén group velocity. Since the group velocity depends on the geomagnetic field and the thermal plasma density along the propagation path, the dispersion measurements have provided a means for remotely probing the magnetosphere. Large collections of data have been analyzed (77-86) to estimate the density distribution.

The propagation paths are confined to L-shells between 4 and 10 and their diurnal distribution confirmed the previous empirical estimate. The frequencies of the ULF whistlers are limited

between 0.2 and 0.7 \widehat{n}_1 (equatorial) and their bandwidths vary from 0.1 to 0.3 \widehat{n}_1 (equatorial). The "best fit" density distribution obtained from the data falls off more rapidly than the well-known hydrostatic equilibrium but less rapidly than the plasmapause. This apparent disagreement with the results from VLF whistler analysis may be resolved by recalling that most ULF whistlers are detected only during the recovery phase of geomagnetic storms. At this time the plasmapause is not so sharply defined and is moving outward as shown in Fig. 4, so that ULF whistlers are probably a measure of this dynamic process. The presence of helium ions along the path would distort the dispersion pattern into a nose, but this type of event is rarely detected.

ULF Whistler Polarization. Studies of the signal polarization (26, 87-90) have revealed some unusual and puzzling results.

According to the hydromagnetic wave theory, the polarization of Alfvén mode signals is Jeft-handed with respect to the magnetic field direction. However ground observations have found it consists of a mixture of random, linear, right, and left-hand polarizations. This might have been anticipated from the complicated transmission in and through the ionosphere. Indeed, recent theoretical analysis has shown that ionospheric mode coupling is subject to several conditions which scramble the wave sense. The left-hand sense is expected to dominate at aight, at higher frequencies, and at polar latitudes,

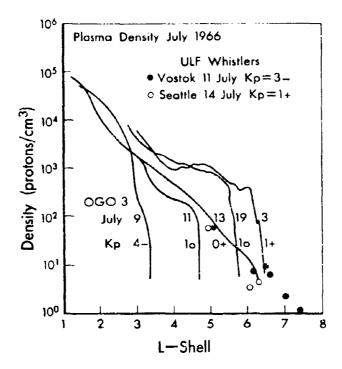


Fig. 4. Plasmapause dynamics observed by OCO-3 and ULF whistler dispersion analysis (85, 86).

which seems to fit some experimental findings. However, observations at conjugate stations have revealed that occasionally the polarization is identical and changes rapidly at both locations suggesting a magnetospheric property.

One aspect of the experimental technique deserves special comment since natural signals are not always ideally suited for polarization measurements. It is important to use only isolated events and narrow band filters to avoid contamination by overlapping signals. Due to phasing of overlapping Fourier components it is quite possible to obtain spurious results if each wave packet element is not well isolated from its neighbors. Narrow band filters also introduce spurious phasing effects which must be accounted for.

Cyclotron-resonance amplification. The long lifetime of wave packets which produce ULF whistlers requires amplification of the signals. The amplitude of successive elements frequently grows for several echoes before decaying slowly away. Furthermore, the complex mode coupling and attenuation in the ionospheric waveguide imposes severe losses at the ends of the path which must be overcome for repetition of the signal. A strong candidate for the source of the signal energy is the cyclotron

resonance interaction with energetic particles along the magnetospheric path. Details of the mechanism are given in the section on propagation theory; only its application to individual ULF whistlers is described here (34, 37, 39, 91, 92).

An example of typical magnetospheric amplification which might be encountered during quiescent times is shown in Fig. 2. Evidently potential bands of amplification are in reasonable agreement with observed propagation bands. The shape and band limits of the theoretical curves depend on the shape of the phase space distribution of energetic particles, and the magnitude depends on the number of particles. If the mechanism is verified, measurements of amplification between successive echoes may become a vital ground-based probe of energetic particle distributions. The fact that ULF whistlers are usually detected only after geomagnetic storms may be attributed to lack of appreciable amplification except during this period.

Both digital and analog methods are currently available for the measurement of successive amplitudes of ULF whistler echoes.

Fig. 5 illustrates the detailed growth and decay of the event shown in Fig. 3. When successive echoes are compared, the effects of ionospheric transmission cancel out and only the ionospheric

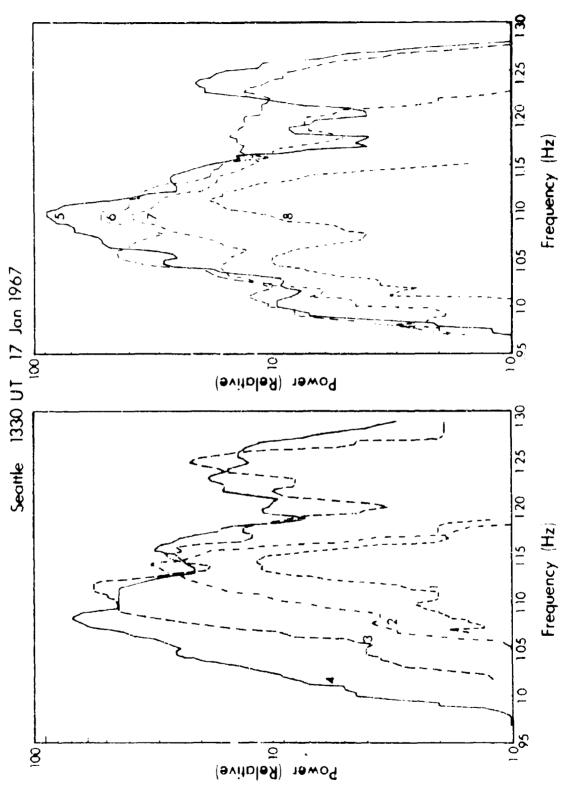


Fig. 5. Detailed amplitude measurements of the eight elements of the ULF whistler event shown in Fig. 3 (91).

planning of joint ground-satellite observations, programs are underway to predict the geomagnetic field-line projection of satellite orbits. Advance notice of opportunities is essential for good coverage of field-aligned phenomena.

The existing permanent network of stations should be supplemented by several portable units that could extend local latitude and longitude chains as well as improve global coverage. The rate at which analog data is reduced to a usable form would be improved substantially by time sharing of new multichannel, ultrafast, frequency-amplitude analyzers. Remote ground stations which record digitally might be interrogated continuously in real time using satellite transponders.

The analysis of ELF signal data on the basis of frequency-time dispersion is well established as a tool of the trade. However, signal amplitude and polarization are also key parameters for understanding the physical processes of the magnetosphere. Amplitude relates directly to wave-particle interactions and polarization is vital for proper mode identification. Physical parameters and indices which characterize known ELF signals should be developed in order to provide a means for routine analysis. Such digested quantities form a useful basis for the evaluation of new theoretical and experimental research and should be collected by the world data center on a variety of geophysical phenomena.

APPENDIX

In order to facilitate joint cooperative research programs between groups of ground observers and ground-satellite observers, lists of rapid-run magnetometer experiments at ground stations and in spacecraft have been prepared. Table 1 contains ground stations, their coordinates, their frequency range according to the Pc classification (1, 0.2-5s; 2, 5-10s; 3, 10-45s, 4, 45-150s; 5, 150-600s), and data analysts. The geomagnetic coordinates in this table are based (106a) on a morth geomagnetic pole at 78.5 N and 291.0 E geographic (longitude is measured eastward from the 291.0 E geographic meridian). Names listed as analysts have published results based on the data recorded at that station and are not necessarily the personnel responsible for its operation. The global distribution of ground stations is shown in Fig. 6. Table 2 contains spacecraft experiments, their orbits, types of instruments, and experimenters.

Preparation of these tables required the assistance of many individuals which the author gratefully acknowledges. Previously published tabulations (102, 106) provided an initial basis on which to build. These were updated by Mrs. H. B. Knaflich of BSRL who made an extensive search of the open literature. Many researchers have contributed revisions and corrections to an early draft that was distributed. Undoubtedly errors and omissions are still present and the author invites interested persons to offer improvements.

. ANALYST	David Orr-UK	V.R.S. Hutton-UK	O. Fambitakoye-Fr	J. Roquet-Fr	A. Onwumechilli-Ni	H.G. Barsczus-Fr	<pre>{ 0.G. Osborne</pre>	J. Roquet-Fr	30	A.M. van Wijk-RSA	M. Kacimi		, V.A. Troitskaya-USSR	S.V. Burtakov-USSR	Ξ	=	Ξ	ı.	Ξ	=	
Pc FREŲ. BAND	2-5	2-4	1-5	1-5		1-5	4	1-5	1-5	2-5	1-5		1-5	1-5	1-5	1-5	1-5	1-5	1-5	1-5	
S NETIC LONG.			88.5		9.41	55.1	57.8	109.2	74.8	7.08	80.1	78.6	133.1	1.50.7	123.2	218.2	127.0	128.	174.4	111.1	112.2
OORDINATES GEOMAGNETIC LAT. LON	12.6 S	03.0 s	04.8 N		10.7 N	21.5 X	14.8 N	05.4 N	12.6 N	33.7 S	25.07 N	05.7 N	30.5 N	33.4 N	53.0 N	44.7 N	62.9 N	57. N	41. N	43.8 N	47.6 N
POSITION COORDINATES PHIC GEOMAGN LONG. LAI.	32.5 E	00.18 W	18.57 E	18.36 E	03.9 E	16.95 W	13.22 W	38.77 E	02.62 E	19.23 E	05.52 E	08.67 E	58.10 E	76.92 E	38.97 E	158.63 E	35.08 E	46.25 E	104.03 E	30.9 E	30.30 E
POS GEOGRAPHIC LAT. LO	00.5 K	05.63 N	04.43 N	09.16 N	07.43 N	14.4 N	08.47 N	N £0.60	09.35 N	34.42 8	22.8 N	03.35 N	37.95 N	43.25 N	58.03 N	53.1 N	67.98 N	62.8 N	52.47 N	46.78 N	50.72 N
SPONSOR	U.K.	U.K.	France	France	היא.	France	Sierra Leone	Ethiopia	France	R.S. Africa	Algeria	Spain	USSR	USSR	USSR	USSR	USSR	USSR	USSR	USSR	USSK
COUNTRY	Uganda	Ghana	Cont. Afr. Rep.	Chad	Nigeria	Senegal	Sierra Leone	Ethiopia	Dahomey	R.S. Africa	Algeria	Fernando Poo Is.	USSR	USSR	USSR	USSR	USSR	USSR	USSR	USSR	USSR
OBSERVATORY	Makerere	regon	* Bangui	<pre>Sanda (Ft. Archambault)</pre>	Ibadan	*M'Bour	Freetown	*Addis Ababa	Parakou	*Hermanus	Tamanrasset	*Moca	Ashkhabad	Alma-Ata	Borok	Petropavlovsk	Lovozero	Sogra	irkutsk	Stepanovka (Odessa)	Kiev

^{*} Standard observatories producing normal magnetograms.

+ + + + + + + + + + + + + + + + + + +	AUNAL 1.3.1	V.A. Troitskaya-USSR	S.V. Burtakov-USSR	Ξ	=	z	Ξ		G. Dodon-1JSSR	R.L. Dowden	E.M. Wescott-US	J.R. Storey M.J. Polletti				J.S. Mainstone-Aus R.W.E. McNicol	B.J. Fraser-Aus	<pre>{ J.S. Mainstone-Aus</pre>	=	B.J. Fraser J.S. Mainstone
Pc FREQ.	BAND	1-5	1-5	15	1-5	1-5	1-5		2-5	1-3	1-5	1-5	1-5	<u>ן</u>	4	1-5	1-5	1-5	1-5	1-5
i.i	LONG.	193.8	237.1	191.4	177.5	161.4	155.3	122.1	176.5		250.		253.6	217 9	6.112		226.	226.9	220.8	,23.
ORDINATES GEOMAGNETIC	LAT.	51.0 N	61.8 N	60,4 N	N 6.39	63.0 N	71.3 N	36.7 N	36.4 N	51. S	7		5 1.69				42.0 S	35.8 S	46.7 S	52.0 s
POSITION COORDINATES HIC GEOMAGN	LONG.	129.67 E	169.83 W	129. E	104.28 E	80.55 E	58.05 E	44.70 E	106.75 E	171. W	16	168.3 E	176 45 17		14/.13 E	146.9 E	151.5 E	152.50 E	145.47 E	147.33 E
PCS: GEOCRAPHIC	LAT.	62.02 N	66.17 N	71.58 N	77.72 N	73.53 N	80.62 N	42.08 N	47.85 N	5 97	66	47.2 S	36 51 6		9.40 S	6.07 S	32.75 S	27.25 S	37.53 S	42.87 S
	SPONSOR	USSR	USSR	USSR	USSR	USSR	USSR	USSR	Mongolia	bacles 7 nov	New Zealand	New Zealand		New Acatana	Australia	Australia	Australia	Australia	Australia	Australia
	COUNTRY	USSK	USSR	USSR	USSR	USSR	USSR	USSR	Mongolia	Land Land	New Zealand	New Zealand	•	New Zealand	New Guinea	New Guinea	Anstralia	Australia	Australia	Australia
	OBSERVATORY	**************************************	Cane Mellen		Caro Cholwnek in	Divon Island	Dixon retains Tithava Bav (Heiss [s.)	Thilisi	Illan Bator		Punedin	Uamaru Invercargill		Auckland	Port Moresby	Lae	DON OF 400 minutes and the second of the sec	U. Ol Newcastle non Esk (Brisbane)	Texters (Melhourne)	Hobart, Tasmania

:

Pc FREQ. BAND ANALYST	J.S. Mainstone-Aus	B.J. Fraser-Aus				(R.R. Heacock-US V.P. Hessler-US J.F. Kenney-US V.A. Troitskaya-USSR W.H. Campbeil-US	D.v. Sabben-N	Utrecht ObsN	32	. V.P. Hessler-US	=	5 F. Eleman-Swe		<pre>{ w.H. Campbell-US T. Nagata</pre>			H. Voelker-Ger	•	=	A. Adair-H E. Verö
Pc FREQ BAND	1-5	1-3				1-5	1-5	1-5		1-5	1-5	1-5	1-5				1.–5	1-5	1-5	2-5
S NETIC LONG.	217.	209.	:	32.5	28.7	357.8	91.2	.06		120.0	112.6	105.3	115.7		98.5	87.7	92.4	94.	93.8	98.3
OORDINATES GEOMAGNETIC LAT. LON	29.0 S	41.8 S		N 6.61	76.1 N	N 6.88	54.1 N	51.4 N		63.8 N	N 6.72	58.5 N	65.3 N		S5.9 N	52.0 N	48.9 N	54.5 N	52.3 N	47.2 N
POSITION COORDINATES HIC GEOMAGN LONG. LAT.	146.73 E	136.54 E		53.52 W	52.90 W	68.65 W	06.67 E	05.65 E		26.63 E	24.65 E	17.13 E	20.42 E	21.70 W	12.45 E	04.6 E	11.28 E	09.73 E	09.95 E	16.72 E
POS GEOGRAPHIC LAT. LO	19.32 S	31.11 S		69.23 N	65.42 N	76.61 N	52.82 N	52.72 N		67.37 N	60.52 N	N 98.68	67.83 N	64.18 N	55.85 N	50.1 N	48.17 N	53.73 N	51.53 N	47.63 N
SPONSOR	Australia	Australia		Denmark	Denmark	Denmark	Netherlands	Netherlands		Finland	Finland	Sweden	Sweden	u.s.	Denmark	Belqium	W. Germany	W. Germany	W. Germany	Hungary
COUNTRY	Australia	Australia		Greenland	Greenland	Greenland	Netherlands	Netherlands		Finland	Finland	Sweden	Sweden	Iceland	Denmark	Belgium	W. Germany	W. Germany	W. Germany	Hungary
OBSERVATORY	Townsville, Qld.	Woomera		Godnavn	Sukkertoppen	Thule	Wittevaen	Noerd Oust Polder		*Sodanky1a	*Nurmijarvi	* Erskoping	*Kiruna	*Reykjavik (Leirvogur)	Rude Skov	Dourbes	*Furstenfeldbruck	*Wingst	Göttingen	* Nagycenk

^{*} Standard observatories producing normal magnetograms.

ANALYST	H. Voelker-Ger	- 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1	E. Selzer	R. Schlich	<pre>{ J. Roquet -Fr { E. Selzer</pre>	W.F. Stuart-UK	Ξ	=	C.C. Ku-Can	W. Campbell-US	J.A. Jacobs-Can	J.A. Jacobs-Can	G. Rostoker-Can	ž	Ξ	Ξ	Ξ	Ξ	T	ε	B. Caner-Can	R.R. Heacock-US
Pc FREQ. BAND	1-5		1-5	1-5	1-5	2-5	2-5	3-5	1-5	1-5	1-5	2-5	2-5	2-5	2~5	2-5	2-5	2-5	2-5	2-5	1-5	^ r1
ETIC LONG.	88.5	74.7	7. 58	79.4	6°78	9.88	82.9	79.0	355.	374.4	0.7 W	300.	300.	300.	300.	300.	300.	300.	301.	300.	293.	258.1
ORDINATES GEONAGNETIC LAT. LON	45.8 N	N 6.84	50.5 N	47.0 N	N 9.67	62.5 N	58.5 N	54.6 N	57. N	66.6 N	58.7 N	61.4 N	60.3 N	71.4 N	85. N	68.5 N	67.3 N	65. N	61.8 N	S9. N	54.2 N	70.4 N
POSITION COORDINATES PHIC GEONAG LONG. LAT.	07.88 E	04.05 W	02.27 E	0.35 W	03.10 E	01.18 W	03.20 W	04.48 W	73.15 W	77.83 W	70.55 W	113.4 W	113.8 W	109. W	105. W	N 6.111	111. W	111.3 W	113.33 W	114.2 W	123.42 W	140.18 W
POSI GEOGRAPHIC LAT. LOI	44.3 N	39.88 N	48.02 N	43.92 N	47.30 N	50.13 N	55.32 N	51.00 N	45.53 N	55.33 N	47.37 N	53.6 N	52.3 N	62.7 N	69.1 N	N 0.09	58.7 N	56.7 N	54.62 N	51.0 N	48.5 N	N 9.60
SPONSOR	Italy	Spain	France	France	France	U.K.	C.K.	U. h.	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada
COUNTRY	Italy	Spain	France	France	France	Scotland	Scotland	England	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada	Canada
OBSERVATORY	*Roburent	*Toledo	*Chambon-la-Foret	*Hurouque	Garchy	Hierwick, Shetiand	Eskdalemuir, Jumfrieshire	Hartland	Mr. St. Hilaire, Que.	Great Whale River	Baie St. Paul, Que.	Leduc (U of Alberta)	Red Deer, Alb.	Ft. Reliance, NWT	Cambridge Bay NWT	Ft. Smith, NWT	Ft. Chepewyan, Alb.	McMurray, Alb.	*Meanook, Alb.	Calgary, Alb.	*Victoria, B.C.	Bar I

* Standard observatories producing normal magnetograms.

ANALYST	R.R. Heacock-US	W.H. Campbell-US	=	H.W. Smith-US F.X. Bostick-US			T.J. Herr m-US	J.F. Kennay-US	=	V. Lincolu-US		A.W. Green, JrUS A.A.J. Hoffman-US	N. Matuura-Japan	=	W.H. Campbell-US	H.W. Smith-US F.X. Bostick-US
Pc FREQ. BAND	1-5			2-5	2-5	2-5	2-5	1-5	1-5	15		1-5	1-5	1-5	1-5	2-5
ETIC LONG.	268.			326.	3.	297.		293.	292.	349.8	3;2.2	327.7	203.5	212.9	266.5	270.
RDINATES GEOMAGNETIC LAT. LON	72. N			40.0 N	57.0 N	50.0 N	50.0 N	52.15 N	53.6 N	N 9.67	40.4 N	43.0 K	3.3 S	4.0 N	21.1 N	21.0 N
POSITION COORDINATES PHIC GEOMAG LONG. LAT.	130. W	116.28 W	145.25 W	97.47 W	68.3 W	118. W	74.5 W	122.35 W	122.19 W	77.38 W	110.83 W	м 52.96	134.53 E	144.75 E	156.26 W	158.0 W
POSITI GEOGRAPHIC LAT. LON	68. N	33.36 N	66.57 N	30.18 N	46.3 N	45.5 N	39.63 N	47.63 N	N 80.84	38.2 N	32.25 N	32.98 N	07.27 N	13.45 N	20.71 N	21.6 N
SPONSOR	Canada	U.S.	U.S.	U.S.	u.s.	u.s.	u.s.	u.s.	U.S.	U.S.	U.S.	u.s.	U.S.	u.s.	u.s.	U.S.
COUNTRY	Canada	U.S.	U.S.	u.s.	u.s.	u.s.	U.S.	u.s.	u.s.	u.s.	u.s.	u.s.	u.s.	u.s.	u.s.	u.s.
OBSERVATORY	Inovik, NWT	Borrego, Calif.	Ft. Yukon, Alaska	Austin, Texas	Ashland, Maine	LaGrande, Oregon	Lebanon, N.J.	Cougar Mt., Seattle, Wn.	Tulalip, Seattle, Wn.	Fredericksburg, Va.	Tucson, Arizona	Dallas, Texas	Koror, Palau Is.	Guam, Mariana Is.	Maui, Hawaii	Dillingham AFB, Hawaii

POSITION COORDINATES

OBSERVATORY	COUNTRY	SPONSOR	POST GLOGRAPHIC LAT. LO	POSITION COORDINATES PHIC GEOMAG LONG. LAT.	RDINATES GEOMAGNETIC LAT. LON	ETIC LONG.	Pc FREQ. BAND	ANALYST
Baguio	Philippines	Philippines	16.52 N	120.6 E	05.1 N	189.2	15	F.N. Glover-Phil "
Cebu	Philippines	Philippines) 5	· ·		
Pamatai	Tahiti	France	17.57 S	149.57 W	15.35 s	77.23	1-5	R. Remiot
Nemambetsu	Japan	Japan	43.54 N	144.12 E	34.0 N	208.4	1-5	Y. Kato-Japan
Kanova	Japan	Japan	31.25 N	130.53 E	20.5 N	198.1	1-5	T. Sakurai
Asc	Japan	Japan	32.53 N	131.01 E	22.0 N	198.1	2-5	T. Hirasawa k Vanaoihara
Simosato	Japan	Japan	33.34 N	135.56 E	23.0 N	202.4	2-5	
Kakioka	Japan	Japan	36.14 N	140.11 E	26.0 N	206.0	1-5	'S. Utashiro
Onagawa	Japan	Japan	38.26 N	141.28 E	28.3 N	206.8	1-5	
Trinidad	B.W. Indies	u.s.	10.42 N	61.38 W	21.0 N	.6	2-5	H.W. Smith-US
Camp Toruguero	Puerto Rico	u.s.	18.29 N	66.25 W	30.0 N	5.	2-5	
	Serina	Netherlands	05.82 N	55.22 W	16.9 N	15.3	2-5	D.v. Sabben-N
Faramation	Peru	Peru	12.1 S	75.3 W	s 9.00	353.8	2-5	
Jicamarca	Peru	u.s.	11.95 S	76.87 W				w.H. Campbell-US
	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	ن =	75.23 S	77.17 W	63.9 S	355.3	1-5	W.H. Campbell-US
Eights	MEGICITES				2 7 02	336	1-5	Ξ
Byrd	Antarctica	u.s.	2 86.6/			•	•	Ξ
Plateau	Antarctica	U.S.	79.47 S	40.58 E				<u>:</u>
South Pole	Antarctica	u.s.	s 00.06	0.0				: :
McMurdo	Antarctica	U.S.	77.85 S	166.62 E				:

	ANALYST	D.M. Finlayson-UK	(V.A. Troitskaya-USSR	S.V. Burtakov-USSR	(T. Nagata-Japan	(T. Oguti J.A. Thomas-Aus	J.A. Thomas-Aus J.A. Annexstad-US W.H. Campbell-US	J.A. Thomas-Aus	R. Schlich-Fr	R.R. Heacock-US	V.P. Hessler-US J.F. Kenney-US V.A. Troitskaya-USSR W.H. Campbell-US	A. DeVuyst	R. Schlich-Fr	R. Schlich-Fr	V.A. Troitskaya-USSR R. Gendrin-Fr
Pc FREQ.	BAND	2-5	1-5	1-5	1-5		1-5	1-5	1-5	1-5		1-5	1-5	1-5	1-5
NETIC	LONG.	24.3	146.8	53.6	7.77	179.2	243.1	103.4	230.9	92.6			140.6	109.3	127.8
ORDINATES GEONAGNETIC	LAT.	65.8 S	77.0 S	66.2 S	8 2.69	77.7 s	61.6 \$	73.1 \$	75.6 S	89.2 S			46.70 S	51.20 s	56.5 S
POSITION COORDINATES PHIC GEOMA	LONG.	26.7 W	93.02 E	11.82 E	39.35 E	110.58 E	158.95 E	62.9 E	140.0 E	106.87 E		24.30 E	77.57 E	51.87 E	70.20 E
OGRA	LAT.	75.52 s	66.55 \$	74.77 S	s 0.69	66.25 \$	54.5 S	67.58 S	8 79.99	78.45 S		70.42 s	37.83 S	46.43 \$	49.35 S
	SPONSOR	U.K.	USSR	USSR	Japan	Australia	Australia	Australia	France	USSR		Belgium- Netherlands	France	France	USSR-France
A STATE OF THE STA	COUNTRY	Antarctica	Antarctica	Antarctica	Antarctica	Antarctica	Antarctica	Antarctica	Antarctica	Antarctica		Antarctica	Indian Ocean	Indian Ocean	Indian Ocean
ORGEDUATORY	COSTINUISM	Halley Bay	Mirny	Novolarzarevskaya	Syowa Bay	*Wilkes	*McQuarie Island	жмаксоп	Towns 1.1 and special formal states of the s	Vostok		Base Kol Baudouin	LaRoche Godon Amsterdam	Port Alfred Crozet	*Kerguelen

* Standard observatories producing normal magnetograms.

R. Schlich-Fr

			POSITI GEOGRAPHIC	POSITION COORDINATES PHIC	RUINATES GEOMAGNETIC	NETIC	Fc FREQ	
OBSERVATORY	COUNTRY	SPONSOR	LAT	LONG.	LAT.	LONG.	BAND	ANALYST
*Resolute Bay	Canada	Canada	74.70 N	M 06.46	83.0 N	9.682		
*Baker Lake	Canada	Canada	64.33 N	A £0.96	73.8 N	315.2		
¢suo11,	Norway	Norway	N 79.69	18.97 E	67.1 N	116.7		
*Ottava	Canada	Canada	45.2 N	75.5 W	57.0 N	351.5		
* Ediabursh	Scotland	Scotland	55.92 N	3.19 ₩	55.3 N	79.4		
*Niemegk	German D.R.	German D.R.	52.07 N	12.68 E	52.2 N	9.96		
* Grocka	Yugoslavia	Yugoslavia	44.63 N	20.77 E	43.6 N	6.001		
*Zaria	Nigeria	Nigeria	11.15 N	7.65 E	13.7 N	79.1		
*Durban	R.S. Africa	R.S. Africa	29.92 S	30.93 E	31.5 S	93.0		

* Standard observatories producing normal magnetograms.

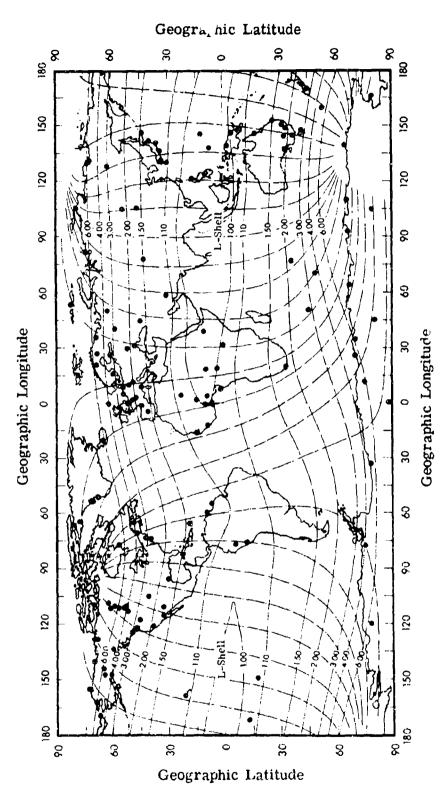


Fig. 5. Global distribution of rapid-run geomagnetic observatories. Geomagnetic coordinates, based on the Jensen and Cain model (107 & 107a), are field-line L-shells and longitude lines spaced at hour intervals.

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TABL
1

U. S. SPACECRAFT MAGNETOMETER EXPERIMENTS

	Water design		TRAJECTORY	<i>ب</i> ر			
VEHICLE	DATES	PERIOD	INCLINATION	PERIGEE/ APOGEE	INSTRUMENT	ENERGY RANGI	ENERGY RANGE EXPERIMENTER
Vela 2B (64-40B)	- 49/1	100.0 hr	39.1°	74490/131530km search coil	search coil		E.W. Greenstadt
OGO 1 (64-54A)	- 49/6	64.3 hr	57.4°	34723/115059кт	search coil		E.J. Smith
Explorer 21 (64-60A)	10/64 -	26.5 hr	33.5°	300/77300 km	fluxgate	± 1000 Y	N.F. Ness D.H. Fairfield
(64-83C)	12/64 - 6/65	106.2 min	89.992°	1040/1089 km	rubidium V.	15,000 - 31,000 Y	A.J. Zmuda F.T. Heuring W. Radford
Explorer 26	12/64 - 10/66	7 hr	33°	300/30000 km	dualaxis fluxgate		L. Cahill
0G0 2 (65-81A)	10/65 -	104.3 min	87.4°	418/1514 km	rubidium v.	1	J.C. Cain A.J.P. Heppner
	10/65 - 10/67				search coil		E.J. Smith
Pioneer 6 (65-105A)	12/65 -			.814/.985 AU	fluxgate		N.F. Ness
060 3 (66-49A)	- 99/9	48.5 hr	62.53	6274/116078km	search coil		E.J. Smith
					rubidium v. fluxgates	0.1-700 Y	J.P. Heppner
Explorer 33 (66-52A)	- 99/9	14-34 days	30-40°	643/4727 - 140000/; J0000 km	triaxial fluxgate	0-64 Y 0-200 Y	N.F. Ness K.W. Behannon C.P. Sonett
Pioneer 7 (66-75A)	- 99/8			1.010/1.125 AU fluxgate	fluxgate	0-32 Y	N.F. Ness F.W. Mariani
ATS-1 (66-110A)	12/66	23.9 hr	.6.0	35779/35794 km 2 fluxgates	2 fluxgates		P.J. Coleman

			TRAJECTORY	1			
	DATES	PERIOD	INCLINATION	PERIGEE/ APOGEE	INSTRUMENT	ENERGY RANGE	ENERGY RANGE EXPERIMENTER
VEHICLE Vela 4A (67-40A)	42.52	111.1 hr	33.7°	108355/114071 km	search coil		E.W. Greenstadt
Explorer 34 (67-51A)	- 19/5	103.6 hr	71.3°	3618/207581 km	triaxial fluxgate	0-32 Y 0-128 Y	N.F. Ness D.H. Fairfield
Dodge (67-66F)	- 19/1	22 hr	7°	40,000 km nearly circular	triaxial fluxgate	0.2-250 Y	A.J. Zmuda M. Dwarkin W. Radford
Explorer 35 (67-70A)	- 19/1	selenocentric orbit	ic orbit		fluxgate	0-2000 Y	C.P. Sonett
		11.5 hr	156°	800/7650 km	triaxial fluxgate	0-24 Y 0-200 Y	N.F. Ness K.W. Behannon C.P. Sonett
0G0 4 (67–73A)	- 19/1	97.0 min	86.0°	409/831 km	fluxgate rubidium v.	0−64 ץ	J.P. Heppner ∾
Pioneer 8 (67-123A)	12/67 -			1.0/1.1 AU	single fluxgate	0-32 Y 0-96 Y	N.F. Ness F. Mariani S. Cantarano
(68-02A)	1/68 -	112.2 min	74°	1078/1580 km	uniaxial fluxgate	± 500 Y	A.J. Zmuda J.C. Armstrong
OGO 5 (68-14A)	3/68 -	63.3 hr	31.1°	271/148186 кт	triaxial fluxgate		P.J. Coleman
					rubidium v.		J.P. Heppner
Pioneer 9 (68-100A)	11/68 -			0.7/1.0 AU	triaxial fluxgate	0-200 Y	C.P. Sonett

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	INSTRUMENT ENERGY RANGE EXPERIMENTER		al N.F. Ness ate D.H. Fairfield		al Meter	al N.F. Ness	al N.F. Ness 5 meter		
	INST	triaxial search coil	triaxial fluxgate	triaxial magnetometer	triaxial magnetometer	triaxial maonetometer	triaxial magnetometer		
	PERIGEE/ APOGEE	400/1087	400+/ 176717 km						
TRAJECTORY	INCLINATION	81.9°	86.83						
	PERIOD	99.6 min	3.4 days	Future	=	=	=		•
	DATES	- 69/9	- 69/9	69	70	71	72		
	VEHICLE	9 000	IMP G	S ³ A	IMP I	AIMP H	AIMP J		

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